

4.4 Parallel and perpendicular lines

- 1** The movement of a robot football match have been mapped on a set of axes where $(0,0)$ is the center of the pitch and the following equations represent the movement of the ball. Identify
- the parallel movements
 - the perpendicular movements
- | | |
|----------------|----------------------|
| a $y = 2x + 5$ | b $y = 5x + 2$ |
| c $y - 5x = 2$ | d $y - 7 = 2x$ |
| e $y - 2x = 6$ | f $y + 0.2x = 6$ |
| g $y = 2x - 5$ | h $y = 2$ |
| i $y = 2x$ | j $y = 5x$ |
| k $y = 0.5x$ | l $y = -0.5x$ |
| m $2x = y$ | n $x = \frac{1}{5}y$ |
- 2 a** Show that a robot going in a straight line through the points $(-4,3)$ and $(11,6)$ will meet a robot going through the point $(1,2)$ and $(2,5)$
- Find the equation representing their movements
 - where they meet
- 3** The ball is moving in the direction $y = 4x + 3$. A robot is standing on $(-1,3)$
- find the equation of the shortest pass to the line representing the movement of the ball.
 - find where the robot will catch the ball.
- 4** Two robots moving in perpendicular direction met at $(4,-4)$ if one of the robots came from $(3,6)$,
- find the equation of the second robot.
 - find the two possible original positions of the second robot if he travels as much as the other robot to reach $(4, -4)$
- 5** A robot comes in the direction $y + \frac{1}{8}x = -3$. The goalkeeper who is standing on $(-10,0)$ wants to send him the ball making the shortest distance.
- Find the equation of the ball making shortest pass between the goal keeper and the other robot.
 - Find where the robot will catch the ball.
- 6** The goal keeper only moves on the line $x = 15$ two strikers are located at S1 $(13,3)$ and S2 $(12,-2)$. Find the best position to stand so that the combined distance from its position to both striker is shortest.

7 The referee only moves on the line $y = 4$ two furthest players are located at P1 $(-8,2)$ and P2 $(10,-2)$. Find the best position to stand so that the combined distance from the referee's position to both players is shortest.

8 The goal is located at G $(-13,0)$, a striker is placed at S $(-9,2)$, if the defense robot can only move on the line $y = \frac{1}{2}x + 5$, find the best position to take so that the combined distance from its position to the goal or the striker is shortest

9 A laser-cutter has been programmed to cut pieces of wood.

Find the resulting shape. The equations it has been programmed with are:

a $y = 2, y = 6.5, x = -1.2, x = 3.1$

b $y = 2, y = 6.5, y = 2x + 3, y = 2x - 3$

c $x = 2, x = -6.5, y = 2x + 3, y = 3x - 1$

Answers

1 i a,d,e,g,i and m or b,c,j and n

ii a and l, a and f

2 a as their gradient are different e.g. $\frac{3}{15} = \frac{1}{5} \neq 3$ so they will meet

b $y = \frac{1}{5}x + \frac{19}{5}$ and $y = 3x - 1$

c $\left(\frac{12}{7}, \frac{29}{7}\right)$

3 a $y = -\frac{1}{4}x + 2.75$

b $\left(-\frac{2}{30}, \frac{82}{30}\right)$

4 a $y = \frac{1}{10}x - 4.4$

b (14,-3) or (-6, -5)

5 a $y = 8x - 10$

b $\left(\frac{56}{65}, -\frac{202}{65}\right)$

6 The shortest point from S_1 to the line is (15,-2)

so the image of S_1 reflected in the line is $S_1'(18,-2)$

the equation of $S_1' S_2$ $y = -x + 23$

$S_1' S_2$ cuts the $x = 15$ at (15,1)

So (15,1) is the best position

7 The shortest point from P_2 to the line is (10,4)

so the image of P_2 reflected in the line is $P_2'(10,8)$

the equation of $P_2' P_1$ $y = \frac{1}{3}x + \frac{14}{3}$

$P_2' P_1$ cuts the $y = 4$ at (-2,4)

So (-2,4) is the best position

8 The shortest point from G to the line is (-12,-1)

so the image of G reflected in the line is $G'(-11,-2)$

the equation of $G' S$ $y = 2x + 20$

$G'S$ cuts the $y = \frac{1}{2}x + 5$ at (-10,0)

So (-10,0) is the best position

9 a 2 set of parallel lines (horizontal and vertical) with same length and a perpendicular angle make a square

b 2 sets of parallel lines (horizontal and diagonal e.g. $y = 2x + \dots$) parallelogram

c 1 set of parallel lines (vertical) the other sides are not parallel so it is a trapezium